

# EMBEDDED MIDDLEWARE ON DISTRIBUTED SMART CAMERAS

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# Agenda

1. (Distributed) Smart Cameras
  - introduction
  - challenges in application development
2. System-level software for smart camera networks
  - SmartCam HW/SW architecture
  - SmartCam middleware services
3. Case study on multi-camera tracking
  - autonomous camera handover
4. Conclusion

# Introduction

- Smart cameras
  - combine **image sensing**, **processing** and **communication** on single **embedded device**
  - perform (high-level) image analysis onboard
  - collaborate in networks of cameras
- These **smart image sensors** are very attractive for various apps, eg.
  - surveillance & security
  - traffic monitoring
  - health care
  - entertainment



# Distributed Smart Cameras (DSCs)

- May help to overcome some hard problems, eg
  - **occlusion** and **low “pixels-on-target”** by exploiting multiple views
  - **high communication bandwidth** by data abstraction and local processing
  - **limits in real-time behavior** by avoiding round-trip delays
  - **failures** of individual cameras by exploiting redundancy
- Challenges for DSCs
  - architecture, network
  - collaboration
  - design process for distributed, embedded vision sensors

# Application Development for DSCs

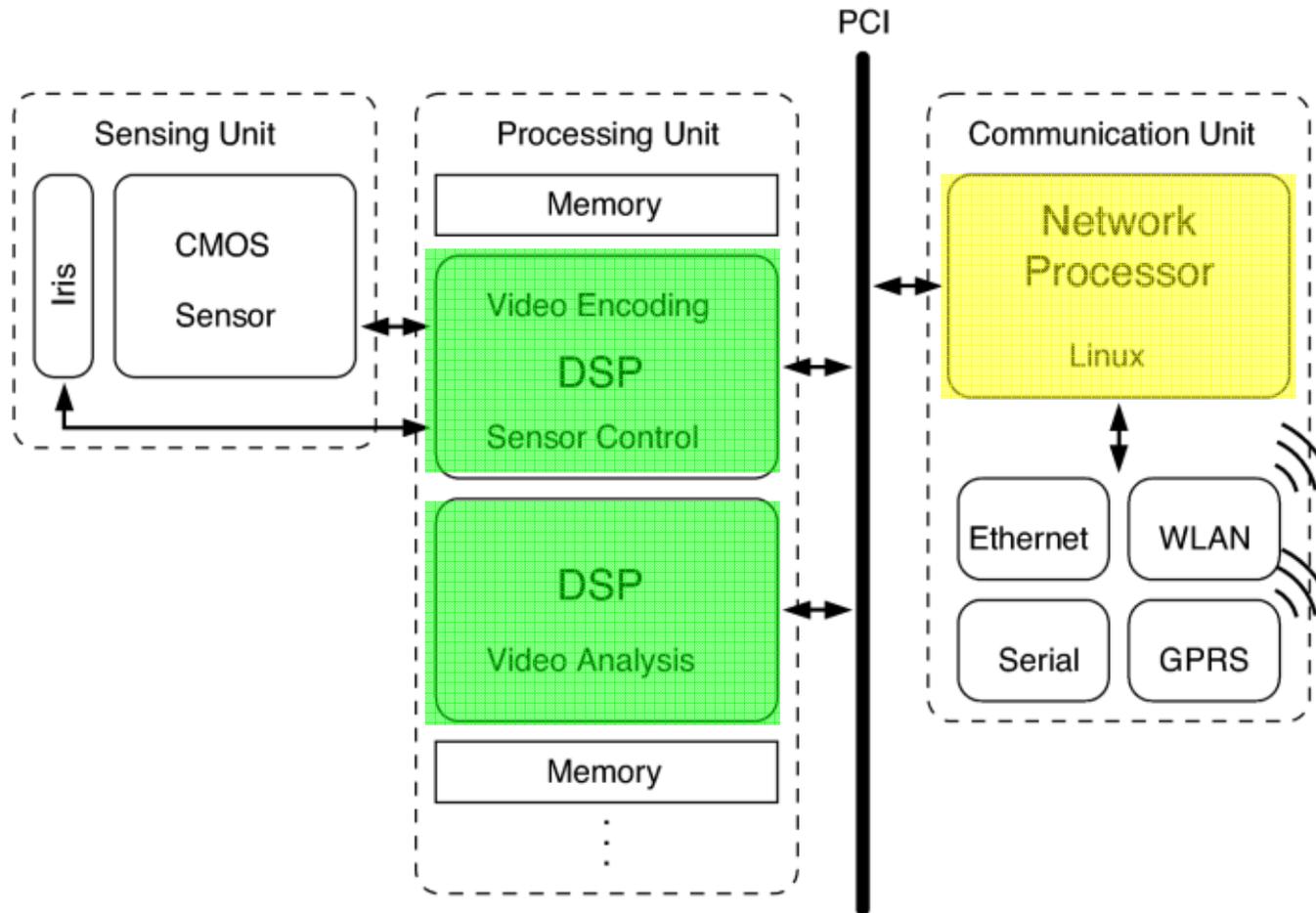
- Much more difficult than single-camera applications
  - collaboration requires communication & control
  - dynamic network (QoS adaptation, scalability, ad-hoc networking)
  - distributed computing (concurrent threads of control)
- **Middleware** would help throughout the development ...
  - design
  - deployment
  - operation/reconfiguration
- **... but available MW does not fit**
  - general “CORBA-like” MW are too heavy
  - WSN MW focus on ad-hoc networking, power awareness

# Middleware Services we'd like to have

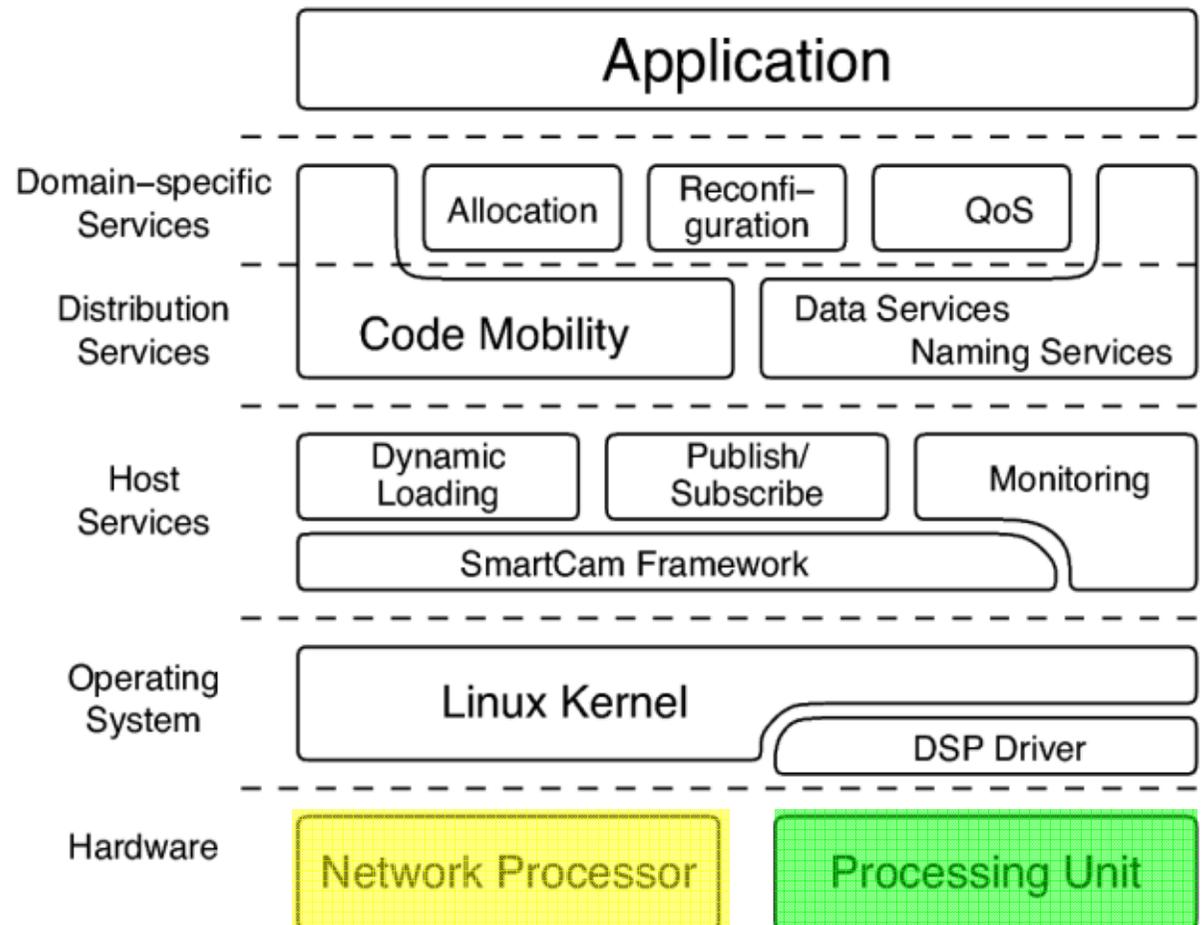
- Deployment services
  - help to initiate the DSC network (loading, allocation, update ...)
- Operational services
  - responsible for efficient coordination and configuration
- Networking services
  - establish transparent communication, data transfer and resource management
- Application-specific services
  - specific to image processing applications, e.g., calibration, registration, QoS adaptation
- **On embedded, resource-limited, image networks**

# Our SmartCam Architecture

[IEEE Computer 2/2006]



# SmartCam Middleware



# SmartCam MW: Host Services

- **Dynamic Loading**
  - change functionality on SmartCam during runtime (“DLL-like”)
  - basis for many other services
- **Publish/Subscribe**
  - provides transparent (inter-processor) communication on SmartCam
- **Monitoring**
  - observes dynamic resource utilization on SmartCam
  - focuses on critical resources on embedded platform (CPU, memory, DMA, PCI bus)

# SmartCam MW: Distribution Services

- Mobile agent system (MAS)
  - foundation for distributed applications
  - provides mechanisms for code and data migration among SmartCams
  - abstracts image processing as tasks (executed on DSP)
- Mobile agent
  - contains application logic and controls image processing tasks
  - improves scalability
- Data and naming services
  - distinguish between control messages and image data

# SmartCam MW: Domain-spec. Services

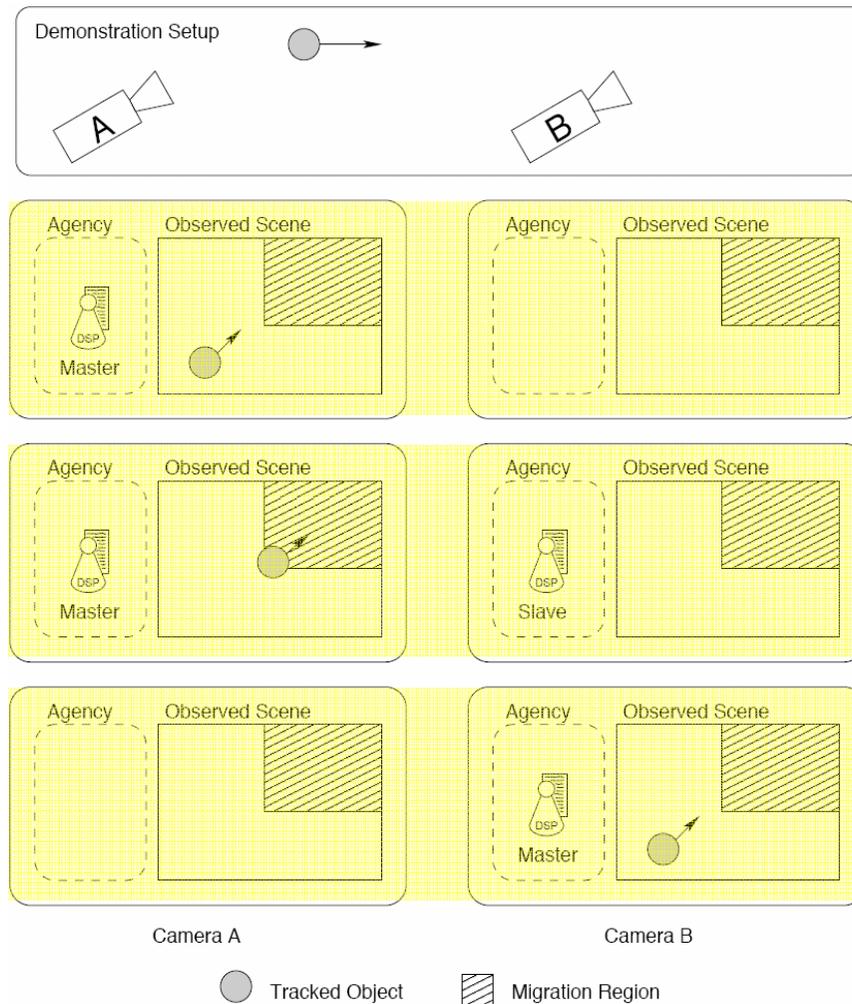
- Allocation
  - assigns image tasks to individual cameras
- Dynamic reconfiguration
  - modifies allocation and functionality (tasks) during runtime
  - requires reasoning about current configuration and resource utilization
- QoS adaptation
  - eg, combined power and QoS

# Autonomous Multi-Camera Tracking

[EURASIP JES 1/2007]

- Develop autonomous multi-camera tracking
  - on embedded smart cameras
  - using an arbitrary tracking algorithm
  - **without central coordination**
- Tracking algorithm
  - standard (“color-based”) CamShift tracker
  - tracker encapsulated in mobile agent
  - one tracking agent for each tracked object/person
- Camera handover
  - based on pre-defined “**migration region**” in camera’s FOV
  - tracking agent autonomously migrates to “next” camera(s)

# Multi-Camera Handover Strategy



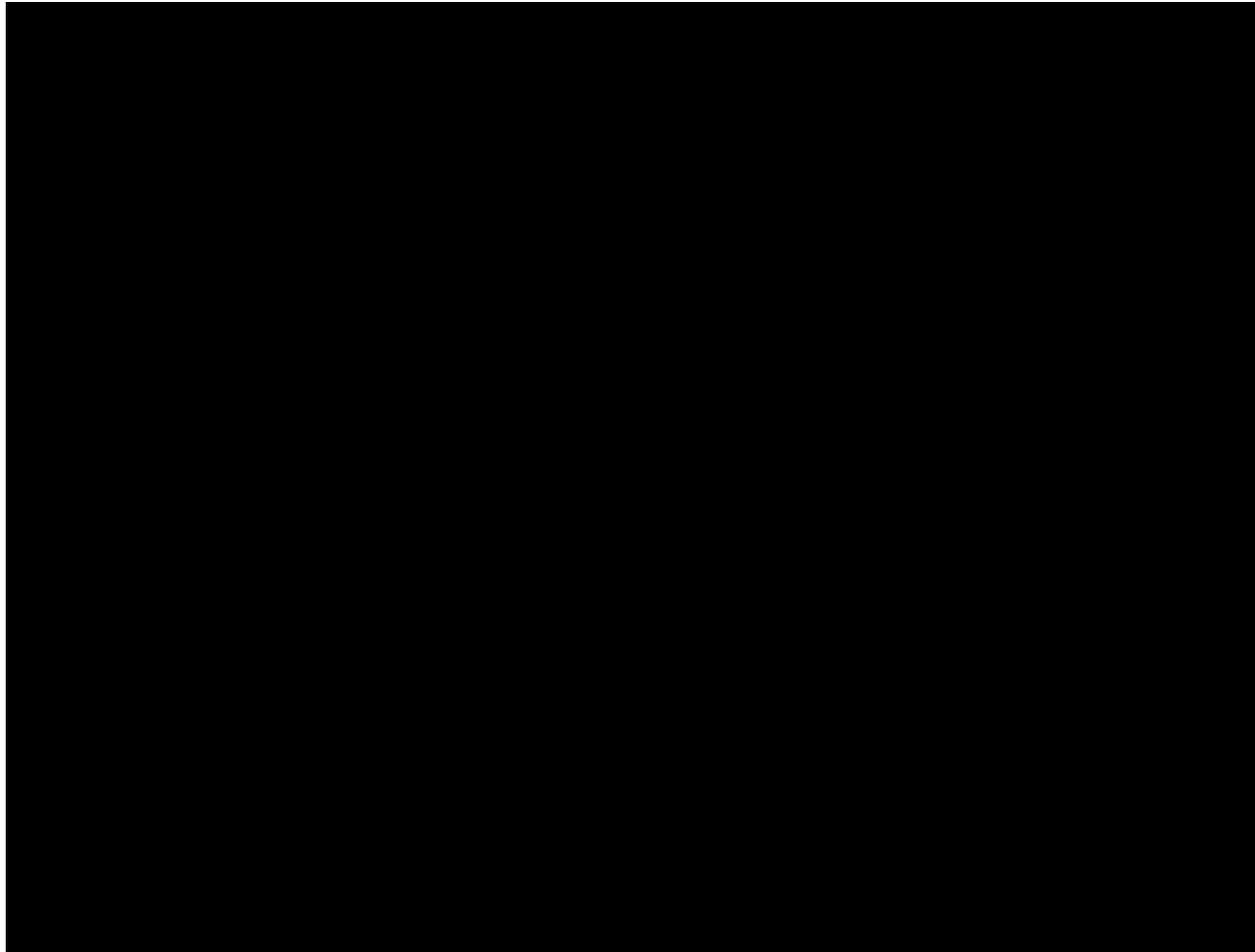
## Master/Slave handover

1. camera A tracks object
2. whenever object enters migration region **tracking agent is cloned** on “next” camera (slave)
3. slave starts tracking  
when slave identifies object  
**master gets terminated**

## Tracker initialization

- color histogram as initialization data

# Multi-Camera Tracking Demo



# Supporting Middleware Services

- Abstraction of image processing
  - Mobile Agent: application logic
  - Tracking algorithm: identify position of object
- Code Migration and dynamic loading
  - Tracker is executed only on the camera observing the object
- Transparent messaging
  - Communication between neighboring cameras
  - Communication between tracking agent and visualizer

# Conclusion

- Distributed Smart Cameras are likely to become an enabling technology for various applications
- Exploit and advance methods from related fields
  - vision, sensor networks, embedded systems, distributed computing, multimedia, ...
- Open Research Challenges
  - architecture & networking
  - collaborative multi-camera vision, sensor fusion
  - (semi-)automatic deployment, eg. calibration, synchronization
  - design support, tools etc.
- Most of these challenges have a strong influence on system-level software (middleware)

# Acknowledgements

This work has taken place at Graz University of Technology.  
Further information available at

[www.iti.tugraz.at/smartcam](http://www.iti.tugraz.at/smartcam)

This research has been partially supported by the Austrian Promotion Agency under grant 810072.

**See you at ICDSC-07 ([www.icdsc.org](http://www.icdsc.org))**

